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Triality Principle for Semisimilarities

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Let M be a left vector space over the (commutative) field K and Q a nondegenerate quadratic form on M . A semilinear transformation S relative to the automorphism σ of K is called a σ -semisimilarity if, for any $x \in M$,

$$Q(xS) = \rho Q(x)^\sigma \quad (1)$$

where $\rho \neq 0$ is a fixed element of K called the ratio of S . Since Q is nondegenerate, S is invertible and S^{-1} is a semilinear transformation relative to σ^{-1} . From (1) we get

$$Q(xS^{-1}) = \rho^{-\sigma^{-1}} Q(x)^{\sigma^{-1}},$$

that is, S^{-1} is a σ^{-1} -semisimilarity of ratio $(\rho^{-1})^{\sigma^{-1}}$.

Now if C is a Cayley algebra over a field K of characteristic different from 2 corresponding to the nondegenerate quadratic form Q , there exists an involution $x \rightarrow \bar{x}$ in C such that $Q(x) = x\bar{x}$ (see [3], sect. 1). It is well known that given a similarity S of the underlying vector space of C relative to the quadratic form Q there exist similarities S_1 and S_2 such that either

$$(xy)S = (xS_1)(yS_2) \quad (2)$$

or

$$(xy)S = (yS_1)(xS_2) \quad (3)$$

holds for all $x, y \in C$.

We get (2) if and only if S is a proper similarity and (3) if and only if S is improper. In both cases S_1 and S_2 are uniquely defined up to a scalar factor and they are proper in case (2) and improper in case (3) (see [2], Thm. 1 and Cor. 1a, 1b).

Since S_1 and S_2 are defined up to a scalar factor, if \bar{S} denotes the coset of S in the projective group of similarities $PS(Q)$ the mappings $\psi_i : \bar{S} \rightarrow \bar{S}_i$, $i = 1, 2$, are uniquely defined and their restrictions φ_i to the projective group of proper similitudes $PS^+(Q)$ define automorphisms of $PS^+(Q)$. If E is the

improper involution of the orthogonal group $O(Q)$ defined by $\alpha E = \bar{\alpha}$, let ϵ denote the automorphism of $PS^1(Q)$, $\bar{U}^\epsilon = \bar{E}UE$. Then φ_1 , φ_2 , and ϵ generate a group isomorphic to the symmetric group S_3 . (See [2], Cor. 2 of Thm. 1.)

In Theorem 1 of the present paper we extend formulas (2) and (3) to semisimilarities and we get as a consequence that the automorphisms φ_i , $i = 1, 2$, of $PS^1(Q)$ can be extended to automorphisms of the projective group of proper semisimilarities $PFS^1(Q)$. In Section 2 we apply this result to express the group of automorphisms of $PS^1(Q)$ as a semidirect product of $PFS^1(Q)$ by the symmetric group S_3 .

1. We assume always that we are dealing with fields of characteristic $\neq 2$.

If M_1 and M_2 are subspaces of the vector space M with a nondegenerate quadratic form Q , a $1-1$ semilinear transformation U from M_1 onto M_2 relative to the automorphism σ is called a σ -semisimilarity of ratio ρ from M_1 to M_2 if

$$Q(yU) = \rho Q(y)^\sigma \quad \text{for all } y \in M_1.$$

We establish first an extension of Witt's theorem to semisimilarities (see, e.g., [1], Thm. 3.9).

LEMMA 1. *Let M be a vector space with a nondegenerate quadratic form Q and let U be a σ -semisimilarity of ratio ρ from M_1 to M_2 . Then U can be extended to a σ -semisimilarity of M if and only if there exist σ -semisimilarities of M of ratio ρ .*

Proof: The "only if" part is obvious, so we need prove that if there exists a σ -semisimilarity S of M of ratio ρ then U can be extended to M .

Let S^{-1} be the inverse of S . Then, for any $x \in M_1$, the mapping $x \rightarrow xUS^{-1}$ defines an isometry between M_1 and M_2S^{-1} for

$$Q(xUS^{-1}) = (\rho^{-1})^{\sigma^{-1}} Q(xU)^{\sigma^{-1}} = (\rho^{-1})^{\sigma^{-1}} (\rho Q(x)^\sigma)^{\sigma^{-1}} = Q(x).$$

By Witt's theorem, this isometry can be extended to an isometry T of M . Then for $x \in M_1$ $xT = xUS^{-1}$, that is, $xTS = xU$ and since TS is defined over M it gives an extension of U to M .

From now on Q will be the quadratic form $Q(x) = x\bar{x}$ of a Cayley algebra C . If a semilinear transformation relative to σ of the underlying vector space of C has the property that $(xy)S = (xS)(yS)$ we say that S is a σ -semiautomorphism of the algebra C .

LEMMA 2. *If there exists a σ -semisimilarity S of ratio ρ of Q , then there exists a σ -semiautomorphism T of C .*

Proof: Let 1 be the identity element of C and $1S = x$. Then $Q(x) = Q(1S) = \rho Q(1)^\sigma = \rho$. If $R_{x^{-1}}$ is the similarity $yR_{x^{-1}} = yx^{-1}$ the transformation $S' = SR_{x^{-1}}$ is a σ -semisimilarity of ratio 1 which leaves invariant the element 1 . Let e_1, e_2 be any two nonisotropic mutually orthogonal elements of the subspace orthogonal to 1 ; then the vectors $f_1 = e_1S'$ and $f_2 = e_2S'$ are mutually orthogonal and $Q(f_i) = Q(e_i)^\sigma \neq 0$, moreover $Q(f_1f_2) = Q(f_1)Q(f_2) = Q(e_1)^\sigma Q(e_2)^\sigma = Q(e_1e_2)^\sigma$. Hence the semilinear transformation T relative to σ defined by $1T = 1, e_1T = f_1, e_2T = f_2, (e_1e_2)T = f_1f_2$ is a σ -semisimilarity of ratio 1 from the underlying vector space of the quaternion subalgebra $M_1 = [1, e_1, e_2, e_1e_2]$ to the underlying vector space of the quaternion subalgebra $M_2 = [1, f_1, f_2, f_1f_2]$, even more, T is a " σ -semisomorphism" from the quaternion subalgebra M_1 to the quaternion subalgebra M_2 . Now let e_3 be a nonisotropic vector in M_1^\perp , that is, e_3 belongs to the subspace orthogonal to M_1 , then by Lemma 1 we know that there exists an element $f_3 \in M_2^\perp$ such that $Q(f_3) = Q(e_3)^\sigma$. If we extend T to a σ -semilinear transformation of the underlying vector space of C by defining

$$e_3T = f_3, \quad (e_1e_3)T = f_1f_3, \quad (e_2e_3)T = f_2f_3, \quad ((e_1e_2)e_3)T = (f_1f_2)f_3,$$

T is a σ -semiautomorphism of C .

THEOREM 1 (Triality principle). *If S is a σ -semisimilarity of Q of ratio ρ , then there exist σ -semisimilarities S_1 and S_2 such that either*

$$(xy)S = (xS_1)(yS_2) \quad \text{or} \quad (xy)S = (yS_1)(xS_2).$$

Moreover S_1 and S_2 are defined up to a scalar factor and only one of the above equalities holds.

Proof: By Lemma 2 we know that there exists a σ -semiautomorphism T of C , thus T is a σ -semisimilarity of ratio 1 . Hence ST^{-1} is a similarity and since the triality principle holds for similarities we can find similarities U_1 and U_2 such that

$$(xy)ST^{-1} = (xU_1)(yU_2) \quad \text{if } ST^{-1} \text{ is proper} \quad (4)$$

or

$$(xy)ST^{-1} = (yU_1)(xU_2) \quad \text{if } ST^{-1} \text{ is improper.} \quad (5)$$

But T is a σ -semiautomorphism of C , therefore $(xy)S = (xU_1T)(yU_2T)$ if (4) holds and $(xy)S = (yU_1T)(xU_2T)$ if (5) holds. Taking $U_1T = S_1$ and $U_2T = S_2$ we get the first part of the theorem.

As to the uniqueness up to a scalar factor, this is an immediate consequence of the uniqueness of the decomposition for similarities.

We can define now the proper semisimilarities as those for which

$(xy)S = (xS_1)(yS_2)$ holds. Then it is clear that the proper semisimilarities form a subgroup of index 2 of the group of semisimilarities.

Remark. Given a quadratic form Q over an even dimensional space whose discriminant is a square (different from zero), if x_1, x_2, \dots, x_{2m} is an orthogonal basis such that $Q(x_1)Q(x_2) \cdots Q(x_{2m}) = 1$ we can define the proper (improper) σ -semisimilarities S as those for which the element $x_1x_2 \cdots x_{2m}$ of the Clifford algebra $C(Q)$ is mapped into itself (minus itself) under the σ -semiautomorphism of $C(Q)$ associated to S (see [4], section II). It is easily seen that this definition coincides with the preceding one because it can be proved that any σ -semiautomorphism of the Cayley algebra C is a proper σ -semisimilarity in the sense just defined. The proof is immediate when C is a split Cayley algebra and can be reduced to this case by extension of the base field if C is a division algebra.

Actually even when the discriminant of the nondegenerate quadratic form Q is not a square the distinction between proper and improper semisimilarities can be applied to the σ -semisimilarities if there exists an element β in the quadratic class of the discriminant of Q such that $\beta^\sigma = \beta$.

2. Let \bar{S} denote the coset of the proper semisimilarity S in the projective group of proper semisimilarities $PTS^+(Q)$. By using the triality principle in the extended form given in Theorem 1, we can prove like in the case of similarities that the mappings $\bar{S}^{q_i} = \bar{S}$, $i = 1, 2$, define automorphisms of $PTS^+(Q)$. Again, like in the case of similarities, if we substitute xy for x and \bar{y} for y in $(xy)S = (xS_1)(yS_2)$ we get $Q(y)^\sigma(xS) = ((xy)S_1)(\bar{y}S_2)$ and multiplying on the right by $\bar{y}S_2 = yES_2E$ we obtain

$$(xy)S_1\rho = (xS)(\bar{y}S_2) \quad \text{for any } Q(y) \neq 0, \quad (6)$$

where $\rho = Q(yS_2)Q(y)^{-1}$ is the ratio of S_2 . This implies that (6) is true for all $x, y \in C$.

Equality (6) says that $\bar{S}^{q_1^2} = \bar{S}$ and $\bar{S}^{q_1q_2} = E\bar{S}^{q_2}E = \bar{S}^{q_2\epsilon}$. Similarly, substitution of \bar{x} for x and xy for y gives $\bar{S}^{q_2^2} = \bar{S}$ and $\bar{S}^{q_2q_1} = \bar{S}^{q_1\epsilon}$. Thus the automorphisms φ_1, φ_2 , and ϵ satisfy the relations $\varphi_1^2 = \varphi_2^2 = \epsilon^2 = 1$ and $\varphi_1\varphi_2 = \varphi_2\epsilon, \varphi_2\varphi_1 = \varphi_1\epsilon$, which imply that φ_1 and ϵ generate a subgroup isomorphic to the symmetric group S_3 (cf. [2], Cor. 2 of Thm. 1, notice that our notation is slightly different from the notation in that paper).

There is a simple interpretation of the isomorphism between S_3 and the group generated by ϵ and φ_1 .

Let $\{D_0\}$ be the set of (6,2) cosets in $PTS^+(Q)$, that is, cosets $\bar{U} \in PS^+(Q)$ which contain an orthogonal involution whose minus space has dimension 2. If U is the (6,2) involution in \bar{U} , let $a, b \in C$ be an orthogonal basis for its minus space, then

$$xU = Q(ab)^{-1}(b(\bar{a}x\bar{a})b)$$

and \bar{U}^{q_1} is the coset of the similarity U_1 defined by

$$xU_1 = b(\bar{a}x) = xL_{\bar{a}}L_b, \quad (7)$$

where L_c means left multiplication by c , while \bar{U}^{q_2} is the coset of the similarity U_2 defined by

$$xU_2 = (x\bar{a})b = xR_{\bar{a}}R_b \quad (8)$$

(see [2], Thm. 1).

Obviously \bar{U}^{q_1} and \bar{U}^{q_2} have order 2, since φ_1 and φ_2 are automorphisms, but they do not contain (6, 2) involutions because if ρ denotes the ratio of U^{q_i} , we get $(U^{q_i})^2 = -\rho$. These involutions of $PS^+(Q)$ were described in [5] as P -involutions. Now the ratio of \bar{U}^{q_1} is equal to the discriminant of the minus space of U and consequently if two cosets $\bar{U}_1^{q_1}$ and $\bar{U}_2^{q_1}$ have the same ratio they are conjugate in $PS^+(Q)$ since they are images of two conjugate (6, 2) involutions. The same is true for $\bar{U}_1^{q_2}$ and $\bar{U}_2^{q_2}$. On the other hand,

$$xEL_{\bar{a}}L_bE = (\overline{b(\bar{a}\bar{x})}) = (x\bar{a})\bar{b} = xR_{\bar{a}}R_b \quad (9)$$

says that the coset $\overline{L_{\bar{a}}L_b}$ is conjugate to $\overline{R_{\bar{a}}R_b}$ by $E \notin S^+(Q)$. Hence, the proof of ([5], lemma 4) implies that the cosets defined by similarities of the form (7) are distinct from the cosets defined by similarities of the form (8).

Let us define then $\{D_1\}$ as the subset of $PS^+(Q)$ consisting of cosets defined by similarities of the form (7) and $\{D_2\}$ as the subset of cosets of similarities of the form (8). Now we know that $\{D_0\}$, $\{D_1\}$, and $\{D_2\}$ are disjoint sets, and it follows from their definitions that

$$\{D_0\}^{q_1} = \{D_1\}, \quad \{D_0\}^{q_2} = \{D_2\}.$$

Moreover, $\varphi_1^2 = 1 = \varphi_2^2$ implies that

$$\{D_0\} = \{D_1\}^{q_1}, \quad \{D_0\} = \{D_2\}^{q_2}.$$

Using the relation $\varphi_2\varphi_1 = \varphi_1\epsilon$ we get

$$\{D_1\}^{q_2} = \{D_1\}^{\varphi_1\epsilon\varphi_1} = \{D_0\}^{\epsilon q_1} = \{D_0\}^{q_1} = \{D_1\}$$

and similarly from $\varphi_1\varphi_2 = \varphi_2\epsilon$ we get $\{D_2\}^{q_1} = \{D_2\}$.

So φ_1 can be described as the transposition (0, 1) and φ_2 as the transposition (0, 2). On the other hand, it follows from (9) that ϵ is the transposition (1, 2). Therefore any permutation of 0, 1, 2 can be described as a product of the element φ_1 and ϵ .

It is known that the only case in which the group $PS^+(Q)$ defined by a nondegenerate quadratic form over an 8-dimensional space has exceptional automorphisms is that in which Q is the quadratic form associated to a

Cayley algebra (see [5], Thm. 1). By an exceptional automorphism we mean one which is not of the form

$$\bar{U} \rightarrow \bar{S}^{-1} \bar{U} \bar{S}$$

where $S \in \Gamma S(Q)$, the group of semisimilarities. The automorphisms of this kind form a group isomorphic to $P\Gamma S(Q)$ and they can be characterized as the automorphisms which take $\{D_0\}$ into itself (see [5], lemma 2). Moreover, these automorphisms together with any exceptional automorphism, such as φ_1 , generate the whole group of automorphisms of $PS^+(Q)$ (see [5], Thm. 3). Since $P\Gamma S(Q)$ is generated by $P\Gamma S^-(Q)$ and \bar{E} , we know then that $P\Gamma S^+(Q)$, ϵ , and φ_1 generate the group of automorphisms of $PS^+(Q)$.

Now if we identify S_3 with its image under any isomorphism from S_3 to the group generated by φ_i and ϵ , since φ_1 and ϵ are automorphisms of $P\Gamma S^+(Q)$ we can define the semidirect product G of the group $P\Gamma S^+(Q)$ by S_3 by taking

$$(\sigma, \bar{S})(\sigma_1, \bar{S}_1) := (\sigma\sigma_1, \bar{S}\sigma_1\bar{S}_1)$$

where $(\sigma, \bar{S}) \in S_3 \times P\Gamma S^+(Q)$.

THEOREM 2. *The group of automorphisms of $PS^+(Q)$ is isomorphic to the semidirect product of $P\Gamma S^+(Q)$ by S_3 defined above.*

Proof: It is clear that if we map (σ, \bar{S}) into the automorphism

$$\bar{U}(\sigma, \bar{S}) := \bar{S}^{-1} \bar{U} \sigma \bar{S}$$

we get a homomorphism of G onto the group of automorphisms of $PS^+(Q)$ since the image of G includes all the automorphisms defined by $P\Gamma S(Q)$ and the exceptional automorphism φ_1 . So we only have to prove that the mapping is an injection. Assume then that (σ, \bar{S}) is mapped into the identity and let \bar{U} be a (6,2) coset of $PS^+(Q)$, then

$$\bar{U}(\sigma, \bar{S}) := \bar{S}^{-1} \bar{U} \sigma \bar{S} = \bar{U} \quad .$$

implies that σ maps $\{D_0\}$ into itself. Hence σ is either the identity of S_3 or permutes $\{D_1\}$ and $\{D_2\}$ in which case $\sigma = \epsilon$. But if $\sigma = \epsilon$

$$\bar{T}(\epsilon, \bar{S}) = \bar{S}^{-1} \bar{E} \bar{T} \bar{E} \bar{S} = \bar{T}$$

for all \bar{T} implies that $\bar{E}\bar{S}$ is the coset of the identity and this is impossible since \bar{E} is an improper involution and \bar{S} is proper. Hence $\sigma = 1$ and

$$\bar{T}(1, \bar{S}) = \bar{S}^{-1} \bar{T} \bar{S} = \bar{T}$$

implies that \bar{S} is the coset of the identity, so that our mapping is $1 - 1$.

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